

Labelled and Non-Wellfounded Proof Theory for Bimodal Provability Logic

Proof Society 2025 - Contributed Talk

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- 1 Introduce basic modal provability logic (GL, axiomatisation, arithmetic/Kripke semantics)
- 2 Motivate non-wellfounded proofs for modal provability logic
- 3 Take a look into bimodal provability

Modal Provability Logic - The Basics

Provability as Modality

Let \mathcal{L}^{EA} be the first-order sentences of Elementary Arithmetic (EA) and $\text{Prov}_{\text{EA}}(\ulcorner \cdot \urcorner)$ some standard provability predicate of EA.

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Provability interpretation $*$: $\mathcal{L}^{\square} \rightarrow \mathcal{L}^{\text{EA}}$ s.t.

- 1 $\perp^* = (0 = 1)$
- 2 $p^* \in \mathcal{L}^{\text{EA}}$
- 3 $(A \rightarrow B)^* = A^* \rightarrow B^*$
- 4 $(\square A)^* = \text{Prov}_{\text{EA}}(\ulcorner A^* \urcorner)$

Arithmetic Completeness

Gödel-Löb provability logic (GL):

CPL Classical Propositional Logic

$$K \quad \Box(A \rightarrow B) \rightarrow (\Box A \rightarrow \Box B)$$

$$L \quad \Box(\Box A \rightarrow A) \rightarrow \Box A$$

$$\text{mp} \quad \frac{A \quad A \rightarrow B}{B}$$

$$\text{nec} \quad \frac{A}{\Box A}$$

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Theorem (Löb 1955, Solovay 1976)

For all modal formulas A , $GL \vdash A$ iff for all interpretations $$: $EA \vdash A^*$.*

Kripke Semantics

A model for GL is a structure $\mathcal{M} = \langle W, \prec, V \rangle$ with
a non-empty set of points $W \neq \emptyset$,
a transitive, irreflexive and converse-wellfounded relation $\prec \subseteq W \times W$,
and a valuation function $V : \text{Prop} \rightarrow \mathcal{P}(W)$.

$$\mathcal{M}, x \not\models \perp$$

$$\mathcal{M}, x \models p \text{ iff } x \in V(p)$$

$$\mathcal{M}, x \models A \rightarrow B \text{ iff } \mathcal{M}, x \not\models A \text{ or } \mathcal{M}, x \models B$$

$$\mathcal{M}, x \models \Box A \text{ iff } \mathcal{M}, y \models A \text{ for all } y \in W \text{ with } x \prec y$$

A formula is true on a model ($\mathcal{M} \models A$) if it is true on every point.

Theorem (Kripke Completeness, Segerberg 1971)

$GL \vdash A$ iff for all GL-models $\mathcal{M} \models A$.

Proof Theory for Provability Logic

Labelled Sequents

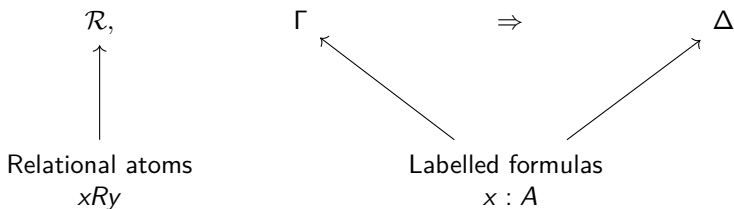
Labelled proof systems can be thought of as formalising some parts of the semantics of a logic.

(They can also be seen as focussed systems for (fragments of) first-order logic.)

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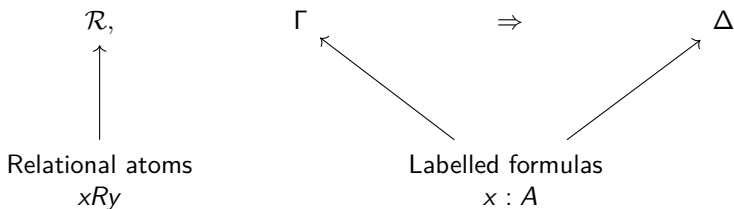
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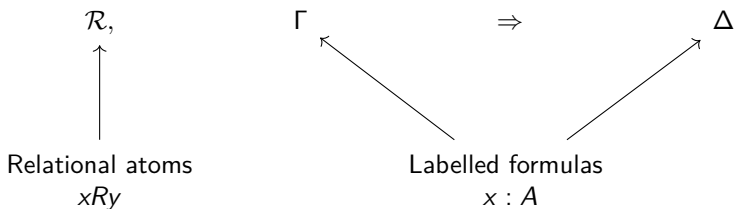
Proof search becomes searching for a countermodel, and thus failed proof search should always give us a countermodel.

Problem for GL:

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Proof search becomes searching for a countermodel, and thus failed proof search should always give us a countermodel.

Problem for GL: Converse-wellfoundedness is a second-order property.

Sequent Calculus 1

The labelled system G3K4 due to Negri, 2005:

$$\text{Id} \frac{}{\mathcal{R}, \Gamma, x : p \Rightarrow x : p, \Delta}$$

$$\perp \frac{}{\mathcal{R}, \Gamma, x : \perp \Rightarrow \Delta}$$

$$\rightarrow_L \frac{\mathcal{R}, \Gamma \Rightarrow \Delta, x : A \quad \mathcal{R}, \Gamma, x : B \Rightarrow \Delta}{\mathcal{R}, \Gamma, x : A \rightarrow B \Rightarrow \Delta}$$

$$\rightarrow_R \frac{\mathcal{R}, \Gamma, x : A \Rightarrow \Delta, x : B}{\mathcal{R}, \Gamma \Rightarrow \Delta, x : A \rightarrow B}$$

$$\Box_L \frac{\mathcal{R}, xRy, x : \Box A, y : A, \Gamma \Rightarrow \Delta}{\mathcal{R}, xRy, x : \Box A, \Gamma \Rightarrow \Delta}$$

$$\Box_R \frac{\mathcal{R}, xRy, \Gamma \Rightarrow \Delta, y : A}{\mathcal{R}, \Gamma \Rightarrow \Delta, x : \Box A} y!$$

$$\text{trans} \frac{\mathcal{R}, xRy, yRz, xRz, \Gamma \Rightarrow \Delta}{\mathcal{R}, xRy, yRz, \Gamma \Rightarrow \Delta}$$

A failed proof of Löb's axiom in G3K4

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$$\overline{\Rightarrow x : \Box(\Box p \rightarrow p) \rightarrow \Box p}$$

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$$\frac{\overline{x : \Box(\Box p \rightarrow p) \Rightarrow x : \Box p}}{\rightarrow R} \Rightarrow x : \Box(\Box p \rightarrow p) \rightarrow \Box p$$

A failed proof of Löb's axiom in G3K4

$$\begin{array}{c} \frac{}{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p} \\ \Box R \frac{}{x : \Box(\Box p \rightarrow p) \Rightarrow x : \Box p} \\ \rightarrow R \frac{}{\Rightarrow x : \Box(\Box p \rightarrow p) \rightarrow \Box p} \end{array}$$

A failed proof of Löb's axiom in G3K4

$$\begin{array}{c} \frac{}{xRy, x : \Box(\Box p \rightarrow p), y : \Box p \rightarrow p \Rightarrow y : p} \\ \Box_L \frac{}{\frac{}{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p} \\ \Box_R \frac{}{x : \Box(\Box p \rightarrow p) \Rightarrow x : \Box p} \\ \rightarrow_R \frac{}{\Rightarrow x : \Box(\Box p \rightarrow p) \rightarrow \Box p}} \end{array}$$

A failed proof of Löb's axiom in G3K4

$$\begin{array}{c}
 \frac{}{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p, y : \Box p} \quad \frac{}{xRy, x : \Box(\Box p \rightarrow p), y : p \Rightarrow y : p} \\
 \rightarrow L \frac{}{\frac{}{xRy, x : \Box(\Box p \rightarrow p), y : \Box p \rightarrow p \Rightarrow y : p}}{\Box L} \\
 \frac{}{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p} \\
 \Box R \frac{}{x : \Box(\Box p \rightarrow p) \Rightarrow x : \Box p} \\
 \rightarrow R \frac{}{\Rightarrow x : \Box(\Box p \rightarrow p) \rightarrow \Box p}
 \end{array}$$

A failed proof of Löb's axiom in G3K4

$$\begin{array}{c}
 \frac{}{\rightarrow L} \frac{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p, y : \Box p \quad \text{Id} \frac{}{xRy, x : \Box(\Box p \rightarrow p), y : p \Rightarrow y : p}}{xRy, x : \Box(\Box p \rightarrow p), y : \Box p \rightarrow p \Rightarrow y : p} \\
 \frac{}{\Box L} \frac{xRy, x : \Box(\Box p \rightarrow p), y : \Box p \rightarrow p \Rightarrow y : p}{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p} \\
 \frac{}{\Box R} \frac{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p}{x : \Box(\Box p \rightarrow p) \Rightarrow x : \Box p} \\
 \frac{}{\rightarrow R} \frac{x : \Box(\Box p \rightarrow p) \Rightarrow x : \Box p}{\Rightarrow x : \Box(\Box p \rightarrow p) \rightarrow \Box p}
 \end{array}$$

A failed proof of Löb's axiom in G3K4

$$\begin{array}{c}
 \frac{}{xRy, yRz, xRz, x : \Box(\Box p \rightarrow p) \Rightarrow y : p, z : p} \\
 \text{trans} \frac{}{xRy, yRz, x : \Box(\Box p \rightarrow p) \Rightarrow y : p, z : p} \\
 \frac{}{xRy, x : \Box(\Box p \rightarrow p) \Rightarrow y : p, y : \Box p} \quad \text{Id} \frac{}{xRy, x : \Box(\Box p \rightarrow p), y : p \Rightarrow y : p} \\
 \frac{}{\Box_R} \quad \frac{}{\rightarrow L} \\
 \frac{}{\Box_L} \frac{}{\Box_R} \frac{}{\rightarrow R} \\
 \frac{}{\Rightarrow x : \Box(\Box p \rightarrow p) \rightarrow \Box p}
 \end{array}$$

A failed proof of Löb's axiom in G3K4

$$\begin{array}{c}
 \vdots \\
 \hline
 \square_L \frac{}{xRy, yRz, xRz, x : \square(\square p \rightarrow p) \Rightarrow y : p, z : p} \\
 \text{trans} \frac{}{xRy, yRz, x : \square(\square p \rightarrow p) \Rightarrow y : p, z : p} \\
 \hline
 \square_R \frac{}{xRy, x : \square(\square p \rightarrow p) \Rightarrow y : p, y : \square p} \quad \text{Id} \frac{}{xRy, x : \square(\square p \rightarrow p), y : p \Rightarrow y : p} \\
 \rightarrow L \frac{}{xRy, x : \square(\square p \rightarrow p), y : \square p \rightarrow p \Rightarrow y : p} \\
 \hline
 \square_L \frac{}{xRy, x : \square(\square p \rightarrow p) \Rightarrow y : p} \\
 \square_R \frac{}{x : \square(\square p \rightarrow p) \Rightarrow x : \square p} \\
 \rightarrow R \frac{}{\Rightarrow x : \square(\square p \rightarrow p) \rightarrow \square p}
 \end{array}$$

A failed proof of Löb's axiom in G3K4

$$\begin{array}{c}
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 \square_L \frac{}{xRy, yRz, xRz, x : \square(\square p \rightarrow p) \Rightarrow y : p, z : p} \\
 \text{trans} \frac{}{xRy, yRz, x : \square(\square p \rightarrow p) \Rightarrow y : p, z : p} \\
 \hline
 \square_R \frac{}{xRy, x : \square(\square p \rightarrow p) \Rightarrow y : p, y : \square p} \quad \text{id} \frac{}{xRy, x : \square(\square p \rightarrow p), y : p \Rightarrow y : p} \\
 \rightarrow_L \frac{}{xRy, x : \square(\square p \rightarrow p), y : \square p \rightarrow p \Rightarrow y : p} \\
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 \rightarrow_R \frac{}{\Rightarrow x : \square(\square p \rightarrow p) \rightarrow \square p}
 \end{array}$$

We end up in a loop! The proof failed and gives us a countermodel consisting of an infinite \leftarrow -chain. **However** it is not a model of GL!

Sequent Calculus 2

In non-wellfounded and cyclic proof theory, proofs are no longer finite trees but can be infinite or may contain cycles.

The non-wellfounded and labelled calculus ℓGL^∞ due to Das, van der Giessen and Marin, 2023:

Definition (informal)

A *proof* in ℓGL^∞ is a possibly infinite tree (of labelled sequents) using the rules of G3K4 where every branch is either finite or has an always increasing R -chain.

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A *proof* in ℓGL^∞ is a possibly infinite tree (of labelled sequents) using the rules of G3K4 where every branch is either finite or has an always increasing R -chain.

Theorem

For any formula $A \in \mathcal{L}^\square$: $\text{GL} \vdash A$ iff there is a proof of $\Rightarrow x : A$ in ℓGL^∞ .

Bimodal Provability Logic

The basic logic CS

$$\mathcal{L}^{\Box\Delta} \ni A ::= \perp \mid p \in \text{Prop} \mid A \rightarrow A \mid \Box A \mid \Delta A$$

Let T and U be r.e. theories which can interpret EA, and let $(\Box A)^* = \text{Prov}_T(\ulcorner A^* \urcorner)$ and $(\Delta A)^* = \text{Prov}_U(\ulcorner A^* \urcorner)$. Then, the following principles hold (provably in EA).

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$$L_{\Delta} \quad \Delta(\Delta A \rightarrow A) \rightarrow \Delta A$$

$$4_{\Box\Delta} \quad \Delta A \rightarrow \Box\Delta A$$

$$4_{\Delta\Box} \quad \Box A \rightarrow \Delta\Box A$$

$$\text{mp} \quad \frac{A \rightarrow B \quad A}{B}$$

$$\text{nec}_{\Box} \quad \frac{A}{\Box A}$$

$$\text{nec}_{\Delta} \quad \frac{A}{\Delta A}$$

A model for CS is a structure $\mathcal{M} = \langle W, \prec, M_0, M_1, V \rangle$ s.t. $\langle W, \prec, V \rangle$ is a GL-model and $M_0, M_1 \subseteq W$.

$\mathcal{M}, x \models \Box A$ iff $\mathcal{M}, y \models A$ for all $y \in M_0$ with $x \prec y$

$\mathcal{M}, x \models \Delta A$ iff $\mathcal{M}, y \models A$ for all $y \in M_1$ with $x \prec y$

Equivalently, we can define a model for CS by having two relations $\prec_{\Box}, \prec_{\Delta}$ s.t. $\prec_{\Box} \circ \prec_{\Delta} \subseteq \prec_{\Delta}$ and $\prec_{\Delta} \circ \prec_{\Box} \subseteq \prec_{\Box}$.

Sequent Calculus 3 (ℓCS^∞ / labCS^∞)

$$\begin{array}{c}
 \text{Id} \frac{}{\mathcal{R}, \Gamma, x : p \Rightarrow x : p, \Delta} \\
 \rightarrow L \frac{\mathcal{R}, \Gamma \Rightarrow \Delta, x : A \quad \mathcal{R}, \Gamma, x : B \Rightarrow \Delta}{\mathcal{R}, \Gamma, x : A \rightarrow B \Rightarrow \Delta} \\
 \square L \frac{\mathcal{R}, xRy, x : \square A, y : A, \Gamma \Rightarrow \Delta}{\mathcal{R}, xRy, x : \square A, \Gamma \Rightarrow \Delta} \\
 \Delta L \frac{\mathcal{R}, xSy, x : \Delta A, y : A, \Gamma \Rightarrow \Delta}{\mathcal{R}, xSy, x : \Delta A, \Gamma \Rightarrow \Delta} \\
 \text{trans}_{RR} \frac{\mathcal{R}, xRy, yRz, xRz, \Gamma \Rightarrow \Delta}{\mathcal{R}, xRy, yRz, \Gamma \Rightarrow \Delta} \\
 \text{trans}_{SR} \frac{\mathcal{R}, xSy, yRz, xRz, \Gamma \Rightarrow \Delta}{\mathcal{R}, xSy, yRz, \Gamma \Rightarrow \Delta} \\
 \perp \frac{}{\mathcal{R}, \Gamma, x : \perp \Rightarrow \Delta} \\
 \rightarrow R \frac{\mathcal{R}, \Gamma, x : A \Rightarrow \Delta, x : B}{\mathcal{R}, \Gamma \Rightarrow \Delta, x : A \rightarrow B} \\
 \square R \frac{\mathcal{R}, xRy, \Gamma \Rightarrow \Delta, y : A}{\mathcal{R}, \Gamma \Rightarrow \Delta, x : \square A} y! \\
 \Delta R \frac{\mathcal{R}, xSy, \Gamma \Rightarrow \Delta, y : A}{\mathcal{R}, \Gamma \Rightarrow \Delta, x : \Delta A} y! \\
 \text{trans}_{SS} \frac{\mathcal{R}, xSy, ySz, xSz, \Gamma \Rightarrow \Delta}{\mathcal{R}, xSy, ySz, \Gamma \Rightarrow \Delta} \\
 \text{trans}_{RS} \frac{\mathcal{R}, xRy, ySz, xSz, \Gamma \Rightarrow \Delta}{\mathcal{R}, xRy, ySz, \Gamma \Rightarrow \Delta}
 \end{array}$$

Progress Condition \approx Every infinite branch has an always increasing $R \cup S$ -chain.

A Natural Bimodal Provability Logic

Let $(\Box A)^* = \text{Prov}_{\text{PA}}(\ulcorner A^* \urcorner)$ and $(\Delta A)^* = \text{Prov}_{\text{ZF}}(\ulcorner A^* \urcorner)$. We gain a maximal bimodal provability logic

$$\text{ER} = \text{CSM}_1 = \text{CS} + \Delta(\Box A \rightarrow A)$$

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In a model of this logic $\langle W, R, M_0, M_1, V \rangle$ a point $x \in M_1$ looks something like this

$$y_1 \longleftarrow y_2 \longleftarrow y_3 \longleftarrow \dots \longleftarrow x$$

such that there is an $n \in \omega$ s.t. for all $m \geq n$: $y_m \in V(p) \leftrightarrow x \in V(p)$.

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such that there is an $n \in \omega$ s.t. for all $m \geq n$: $y_m \in V(p) \leftrightarrow x \in V(p)$.

This calls for a different/new progress condition for a system for ER!

Takeaway

Labelled and non-wellfounded proof theory can give us a simple proof theoretic framework to build upon.
(Formalised first-order and (restricted) second-order reasoning.)

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Future works:

- More extensions
- More modalities (e.g. GLP)
- Proof translations, e.g. sequentialise into unlabelled sequent systems

Thank you for listening!